

Palestine Technical University- Kadoorie (PTUK)

Mechanical Engineering Department

Summer Semester, 2023/2024

12210244: Dynamics

Student ID:

Homework #:

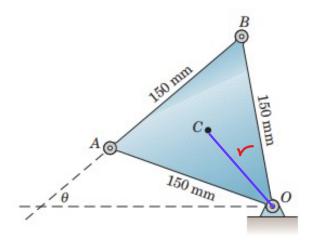
Dr. Hammam S. R. Daraghma

Due Date:

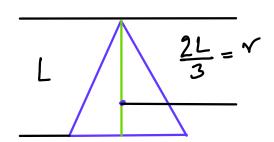
28th, Aug. 2024

Date of Submission:

Exercise 1. The plate OAB forms an equilateral triangle which rotates counterclockwise with increasing speed about point O. If the normal and tangential components of acceleration of the centroid C at a certain instant are $80 \ m/sec^2$ and $30 \ m/sec^2$, respectively, determine the values of $\dot{\theta}$ and $\ddot{\theta}$ at this same instant. The angle is the angle between line AB and the fixed horizontal axis.



Ans.



$$L^{2} = 150^{2} - 75^{2}$$

 $L = 129.9 \text{ mm}$
 $V = 86.6 \text{ mm}$

$$a_{N} = r \omega^{2} \implies 80 = 0.0866 \omega^{2} \implies \omega = 30.4 \frac{rad}{sec}$$

$$a_{t} = \sqrt{\alpha} \implies 30 = 0.0866 \alpha \implies \alpha = 346.4 \frac{rad}{sec}$$

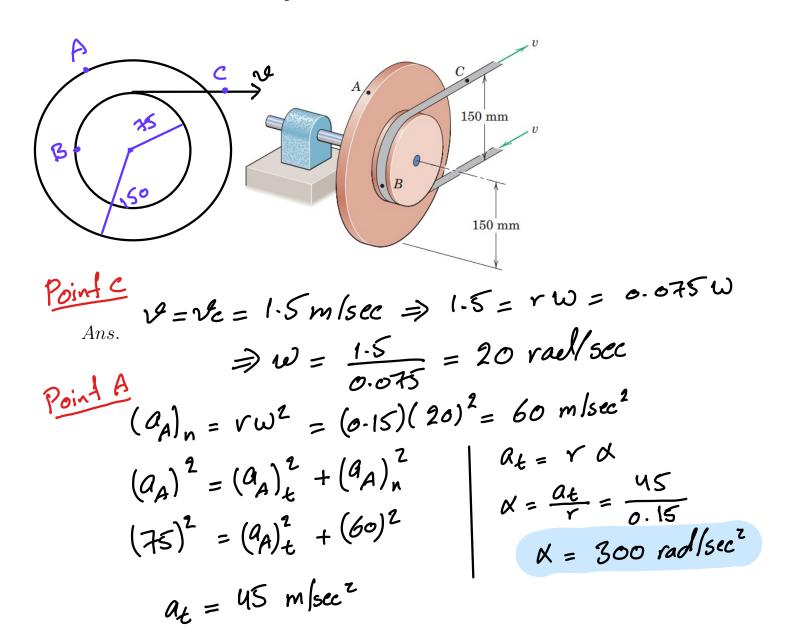
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Course name: Dynamics

Ans.

Exercise 2. The belt-driven pulley and attached disk are rotating with increasing angular velocity. At a certain instant the speed v of the belt is $1.5 \ m/sec$, and the total acceleration of point A is $75 \ m/sec^2$. For this instant determine:

- the angular acceleration of the pulley and disk
- \bullet the total acceleration of point B
- \bullet the acceleration of point C on the belt



Course name: Dynamics

Ans.

$$(a_2) - rW^2 = 0.075 (20)^2 = 30 \text{ m/sec}^3$$

$$(a_B)_N = rW^2 = 0.075 (20)^2 = 30 \text{ m/sec}^2$$

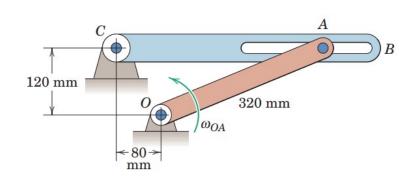
 $(a_B)_t = rX = 0.075 (300) = 22.5 \text{ m/sec}^2$

$$a_{\rm B} = \sqrt{30^2 + 22.5^2} = 37.5 \text{ m/see}^2$$

Just tangential acceleration $a_c = (a_B)_t = 22.5 \text{ m/see}^2$

$$a_c = (a_B)_t = 22.5 \text{ m/sec}^2$$

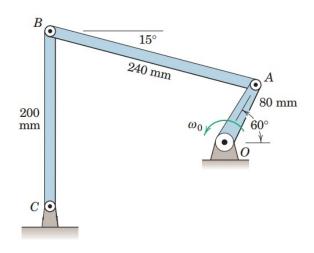
Exercise 3. Link OA has an angular velocity as it passes the position shown. Determine the corresponding angular velocity of the slotted link CB. Solve by considering the relation between the infinitesimal displacements involved



With respect to point 0 $\vec{V}_{A} = W_{0A}\hat{k} \times \vec{V}_{A/0}$ = $8\hat{k} \times (0.32 \cos 22.62\hat{i} + 0.32 \sin 22.62\hat{j})$ $0 \quad W_{0A} = 8 \text{ rad | sec}$ = $-0.96\hat{i} + 2.37\hat{j}$ $0 = \sin^{-1} \frac{120}{320}$ With respect to point $0 = 22.02^{\circ}$ $\vec{V}_{A} = W_{8c}\hat{k} \times \vec{V}_{A/e} + v_{vel}\hat{i}$ $-0.96\hat{i} + 2.37\hat{j} = W_{8c}\hat{k} \times [(0.08 + 0.32 \cos 22.02)\hat{i}$ $+ \text{evel}\hat{i}$ $-0.96\hat{i} + 237\hat{j} = 0.377 \text{ where }\hat{i} + \text{vel}\hat{i}$ $\rightarrow \text{vel}\hat{i}$ $\rightarrow \text{vel} = -0.96 \text{ where } / \text{vel}\hat{i}$

Ans.

Exercise 4. A four-bar linkage is shown in the figure (the ground "link" OC is considered the fourth bar). If the drive link OA has a counterclockwise angular velocity $\omega_O = 10 \ rad/sec$, determine the angular velocities of links AB and BC.



Ans.

with repred to point o

The work of x Tho

The lock (0-08 cos 60 i + 0.08 sin 60i)

-0.69i +0.4j

with repred to point A

With respect to point H

$$\vec{V}_{B} = \vec{V}_{A} + \vec{\omega}_{AB} \times \vec{V}_{BIA} - 0.732 \hat{i} + 0.06 \hat{z}_{j}$$
 $= -0.69 \hat{i} + 0.4 \hat{j} + \omega_{AB} \hat{k} \times (-0.24 \text{ costs} \hat{i} + 0.24 \text{ sints} \hat{j})$

Ans

with respect to point A

with respect to point C

$$\overrightarrow{\mathcal{J}}_{B} = \overrightarrow{\omega}_{BC} \times \overrightarrow{V}_{B(C}$$

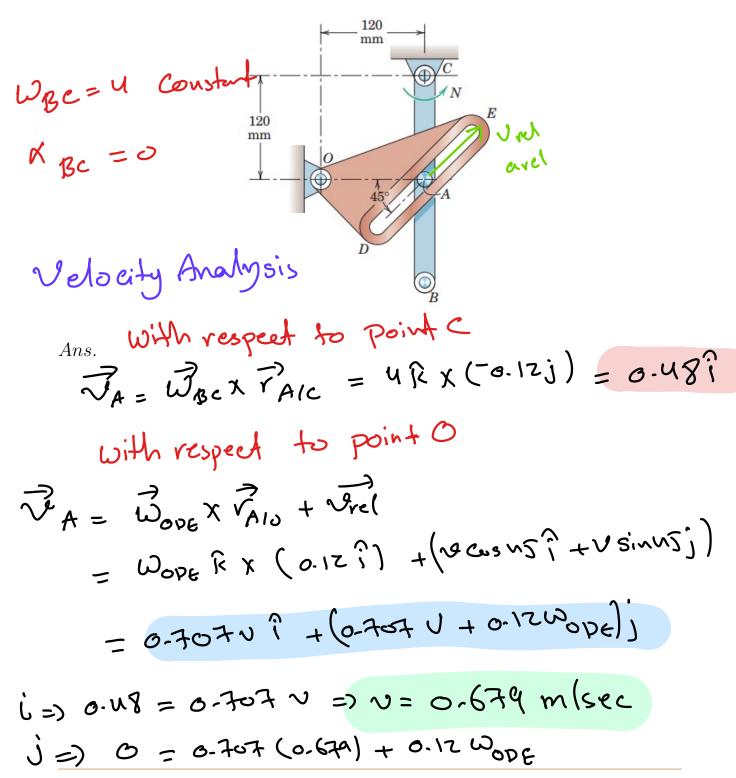
$$= \omega_{BC} \widehat{k} \times (0.2\widehat{j})$$

$$= -0.2 \omega_{BC} \widehat{i}$$

=> (-0.69-0.062 WAB)î+ (0.4-0.232 WAB)ĵ = -0.2 WBî

$$i = -6.69 - 0.062(1.724) = -0.7(WBC)$$

Exercise 5. For the instant represented, link CB is rotating counterclockwise at a constant rate $\omega = 4 \ rad/sec$ and its pin A causes a clockwise rotation of the slotted member ODE. Determine the angular velocity and angular acceleration of ODE for this instant.



10 of 11

=) WODE = - 4 red/sec

Ans. Acceleration analysis

with respect to point C

DA=BCX(BCXTAIC)= 4kx(048)= 1.92j

with respect to point O

QA = BODEX (BODEX PAIO) + ROPE PAIO+ 2 BODEX VICEI + Red

0 = 4 k x (-4 k x o. r.i) = 7.92 i

(2) =) KOPERX (0.12]) = 0-12 KOPEJ

0 = 2 [4 R x (0.679 cosus i+ 0,679 sinusi)]

= 3.84 Î - 3.8uj

0 = a Cos 45î+ asin45j = 0-707 aî +0-707j

BA = (0-707a + 1-92) i + (0-707a-3-84 + 0.12xope)

(=) 8-707 a +1.92=0 =) a = -7.72 m/sec2

j => 0-707 (-7.72) - 3-84 + 0.12 dobe = 192

XOVE = 64